



# PROXIMA

## Mitigating Software Instrumentation Cache Effects in Measurement-Based Timing Analysis



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# Agenda

- ❑ Measurement-Based Timing Analysis (MBTA)
  - Introduction
  - General application process
    - Allocation of ipoints
    - Trace generation
      - Hardware and Software
    - Trace collection and
    - Trace processing
- ❑ Software trace generation
  - Need and problems in the presence of caches
- ❑ Solution Proposal
- ❑ Evaluation: Setup and Results
- ❑ Conclusions

# Introduction to MBTA

## □ MBTA

- Widely used in industry space, automotive, railway, aerospace, ...

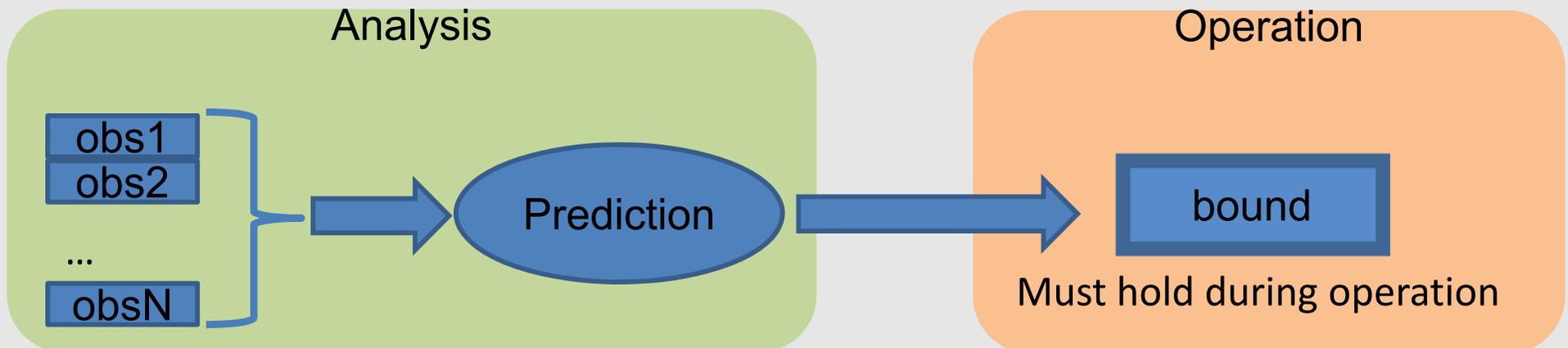
## □ Phases:

### ➤ Analysis phase

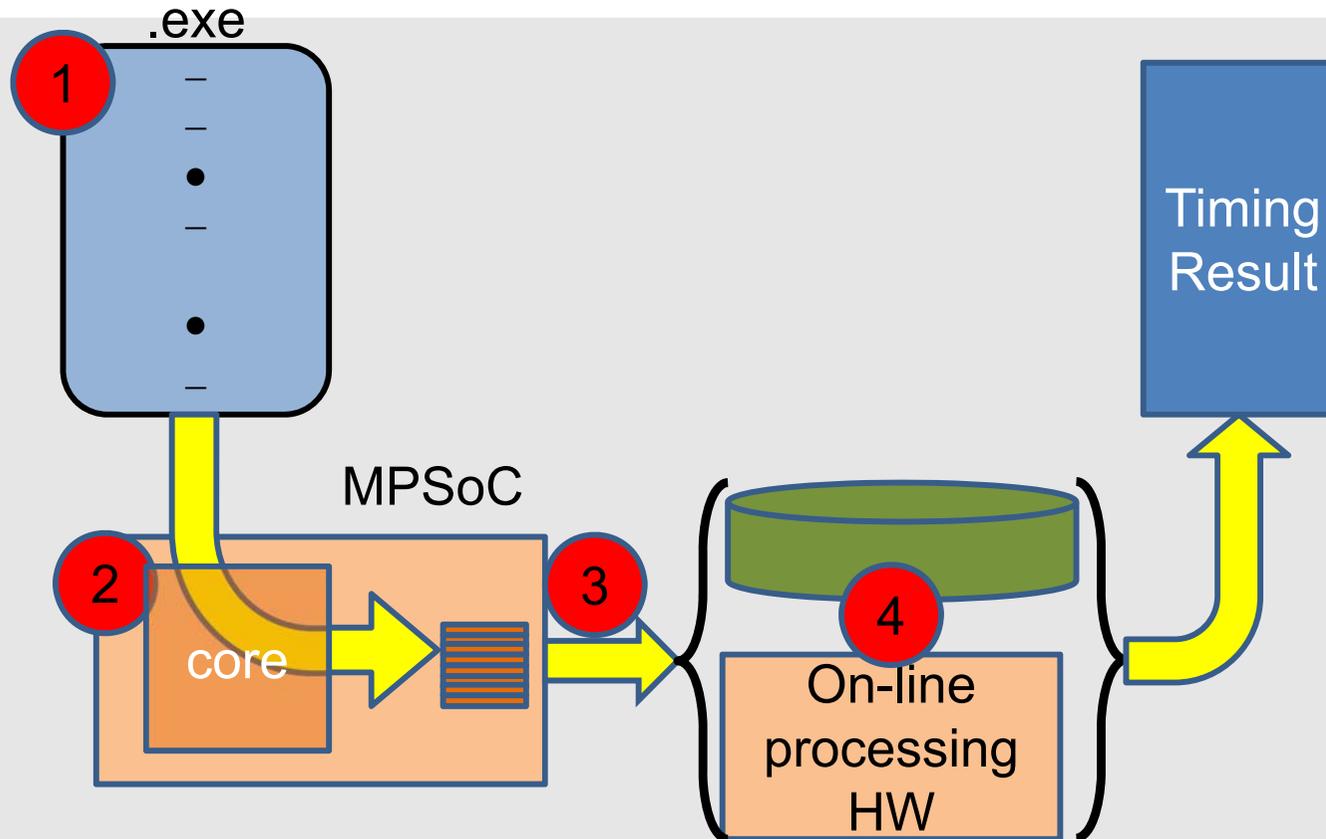
- Collect measurements to derive a WCET estimate that holds valid during system operation

### ➤ Operation phase

- Actual use of the system (under assumption is stays within its performance profile)



# MBTA: General Process



□ Generates a time trace that logs the time at which ipoints are hit

1) Ipoint (●) placement

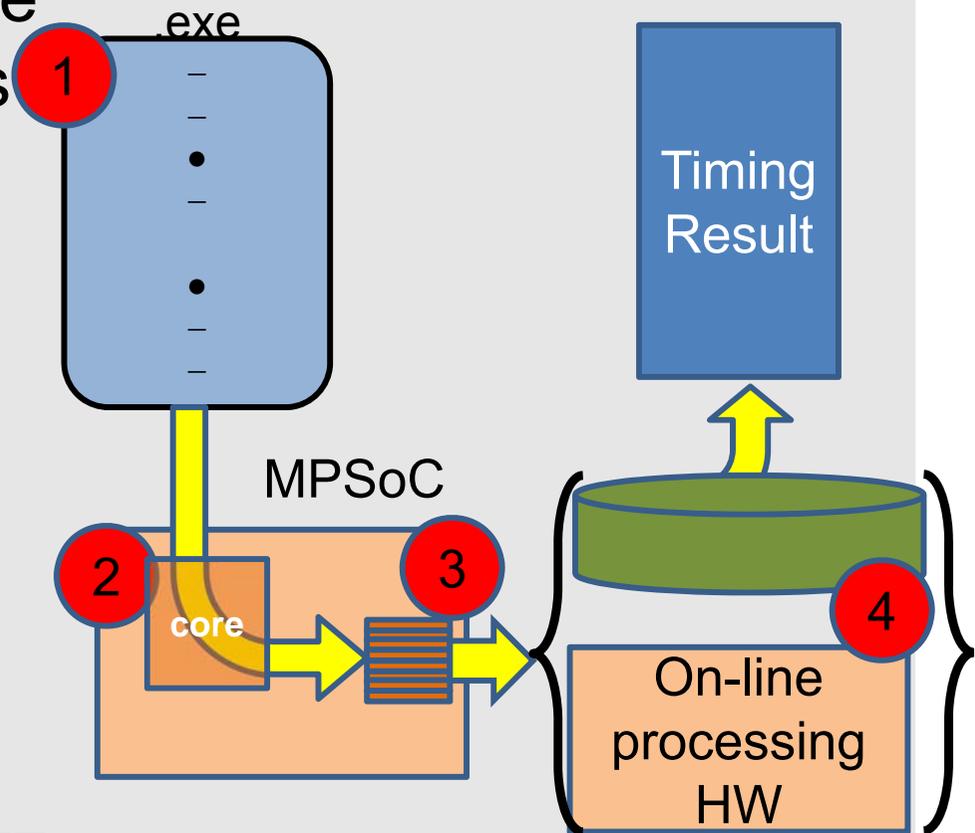
2) Trace generation: 'Read time when hitting an ipoint'

3) Trace collection: 'Get the reading outside the board'

4) Trace processing: 'Make sense of the readings'

# 1. Ipoint location

- ❑ The number and location of the ipoints depend on the analysis
- ❑ Extremes of the spectrum
  - Unit of Analysis (e.g. function)
  - Basic block boundary
- ❑ In general:
  - Identify small program parts/segments (extracted from an analysis of the CFG) [6][1]
  - Segments chosen to
    - facilitate the derivation of a WCET by composing the WCET of each segment [19][1] or
    - to reduce the number of ipoints



# 3. Trace Collection and 4. Processing

- ❑ Instrumented program execution on the target results in a set of timestamps and events

- ❑ Collection

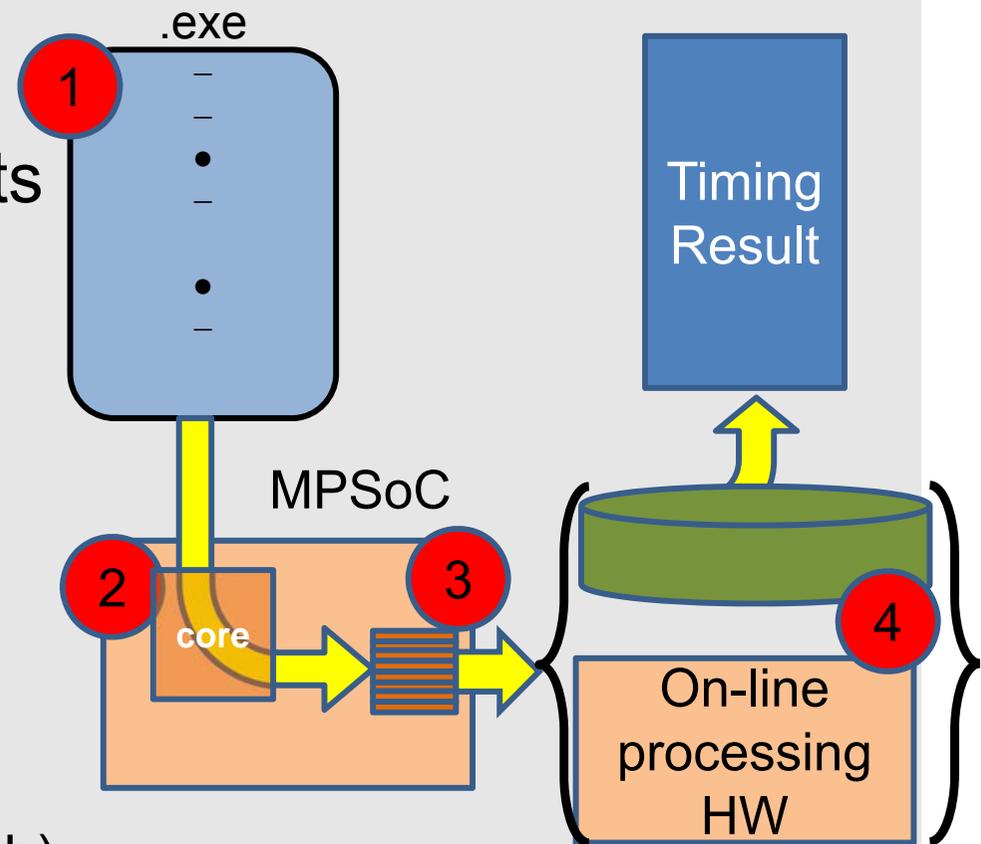
- Out-of-band support exists so trace collection does not impact program execution

- ❑ Processing

- Either on-line via specialized hardware (can be costly)
- Or off-line (trace files can be high)
- Balance ipoint frequency

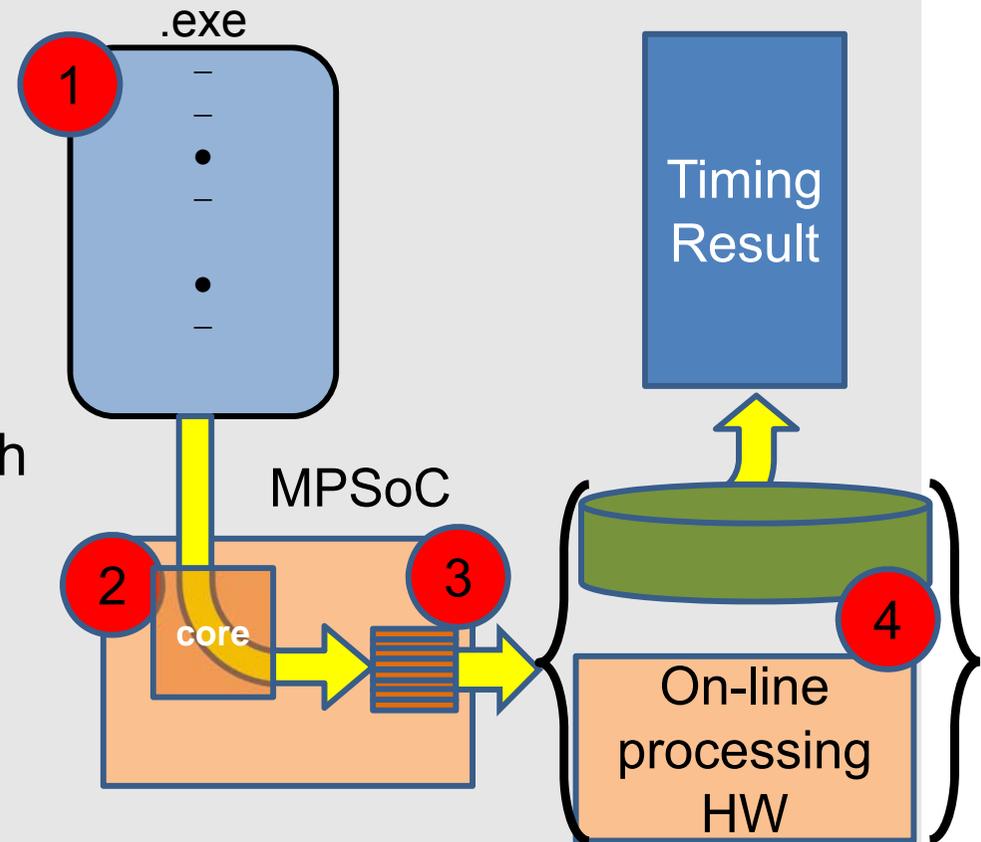
- ❑ Their impact assumed null

- Otherwise, its additive nature will allow to easily factor them in



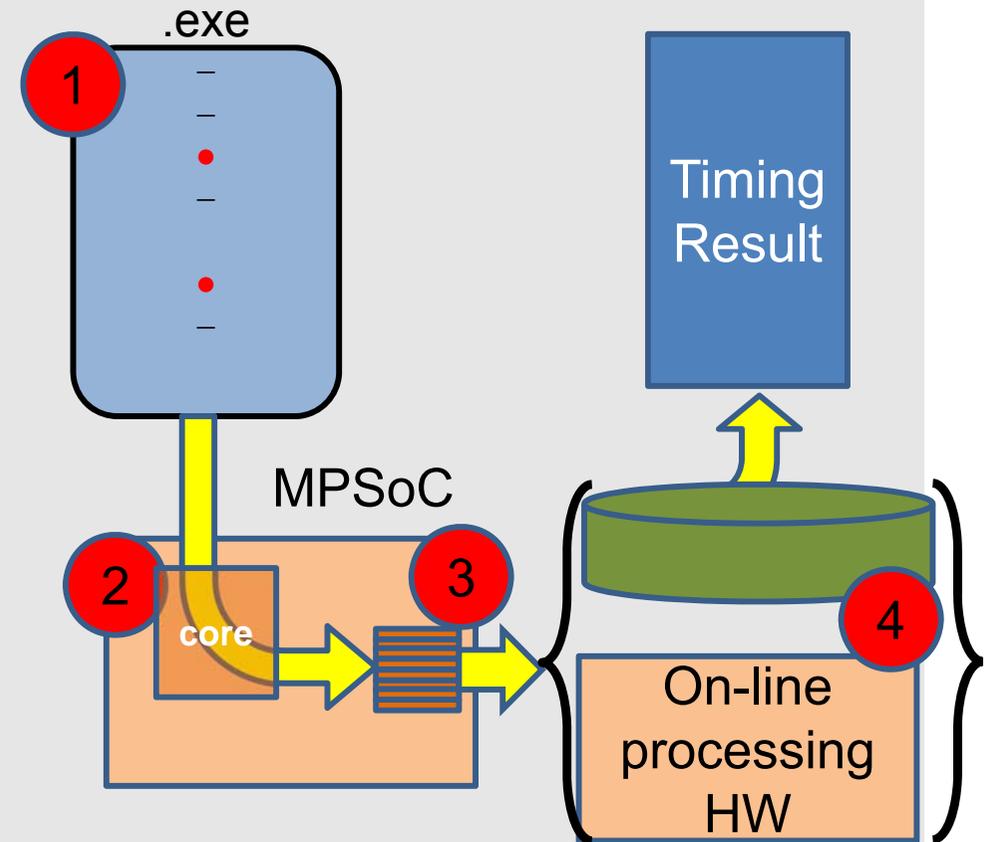
## 2.a. Hardware Trace Generation

- ❑ Advance debug hardware trigger specific actions when certain opcodes are executed
- ❑ Interfaces exist to program:
  - The type of instruction to trace
  - The action to perform when such an instruction is hit
  - E.g. Nexus or GRMON for the LEON processor family
- ❑ In general
  - Debug hardware of that kind is not present in all processors used in real-time systems
  - In many systems software instrumentation support is needed



## 2.b. Software Trace Generation

- ❑ Instrumentation instructions/code (icode) are inserted
  - E.g icode that reads the time-base register and output its contents to a specific I/O address
  - Instrumentation instructions: move time to a special purpose register / memory position
- ❑ Added by the instrumenter



## 2.b. Software Trace Generation: overheads

### □ Direct: execution of executing instrumentation code

- Core:  $\Delta_{icode}^{core-exec}$
- MPSoC (chip):  $\Delta_{icode}^{chip-exec}$

### □ Indirect: change in the layout of program code in memory.

- Ipoints shift the memory position of following instructions → address shift → different cache set layout → different program!
- Evidence that the execution-time the instrumented binary (iprogram) is larger or smaller than those obtained with oprogram?

$$ET_{iprogram} = ET_{oprogram} + \left( \Delta_{icode}^{core-exec} + \Delta_{icode}^{chip-exec} + \Delta_{icode}^{collect} \right) + \Delta_{icode}^{malign}$$

- $\Delta_{icode}^{malign} > 0$  or  $\Delta_{icode}^{malign} < 0$ 
  - With as low as a single instrumentation instruction

# To leave or not to leave (the icode)

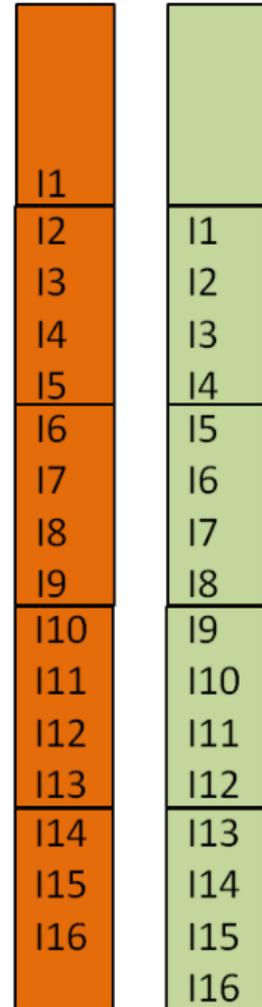
- ❑ Removing icode (from the final executable)
  - How the execution-time observations taken with the *iprolog* correlate with the timing behaviour of the *oprolog*
  - Functional and timing verification conducted on different software
    - Strong additional argument must be provided for the analysis result to hold
- ❑ Leaving icode
  - Cost and complexity to demonstrate equivalent functionality
    - Certification and qualification practices may simply not accept the presence of this instrumenter-added code
  - Likely to worsen memory footprint and average performance
  - Some memory-mapped I/O space – where execution-time readings might be kept – may be unnecessarily wasted

# Removing the code: example

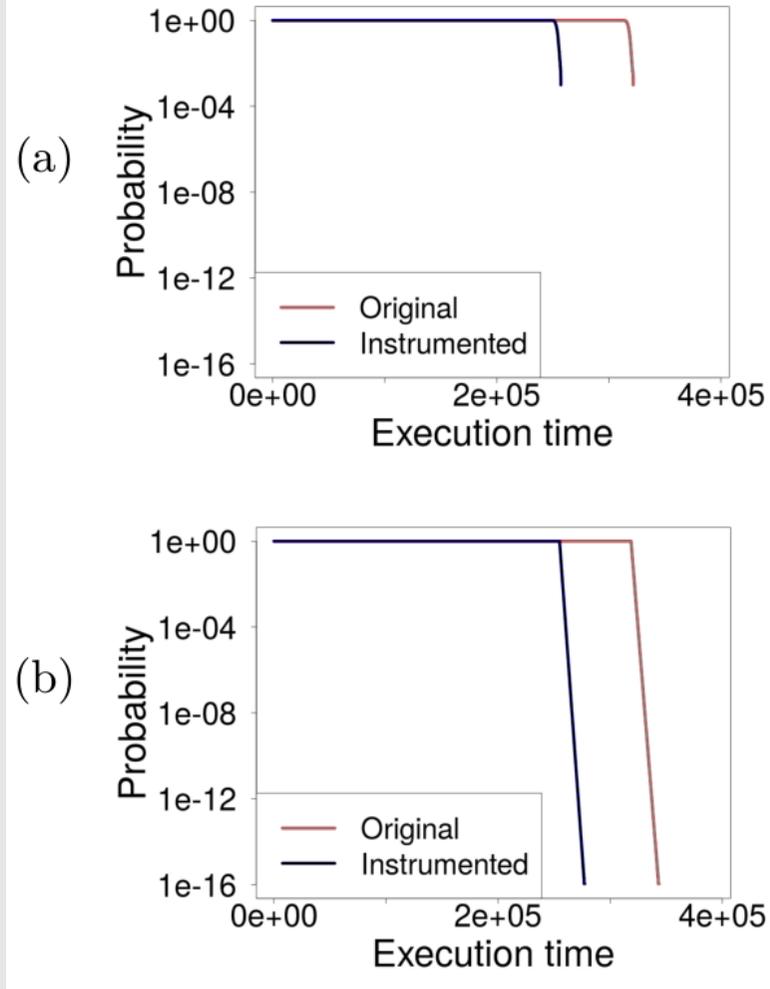
```

for {
  switch() {
    case X:
      I4
      ...
      I6
    case X: Y
      I7
      ...
      I10
    default:
      I11
      ...
      I15
  }
}
    
```

Memory view split  
in cache lines

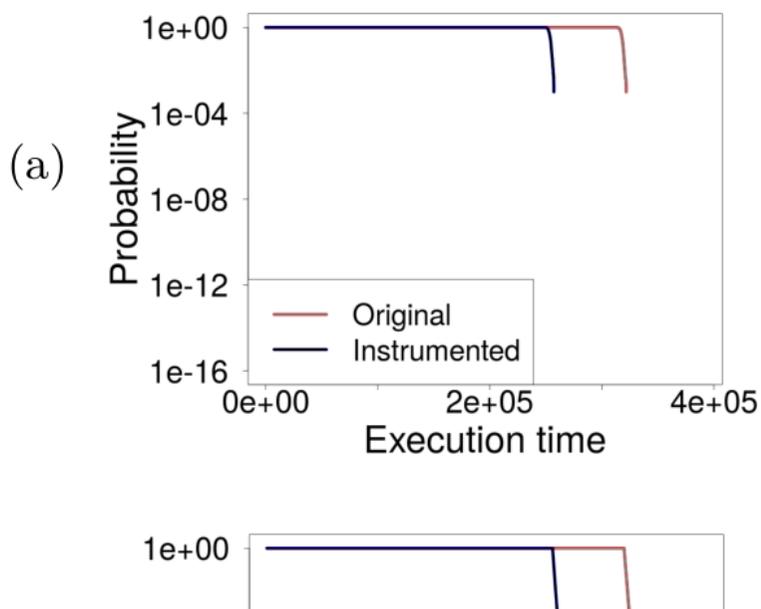
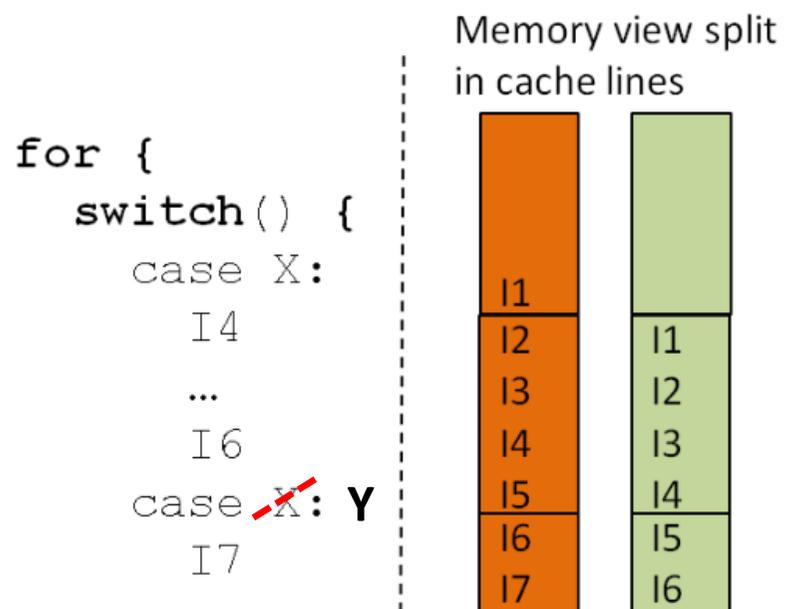


(a) no inst. (b) inst.

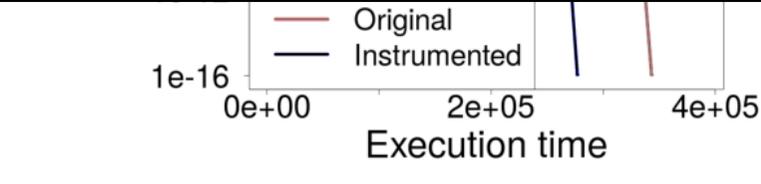
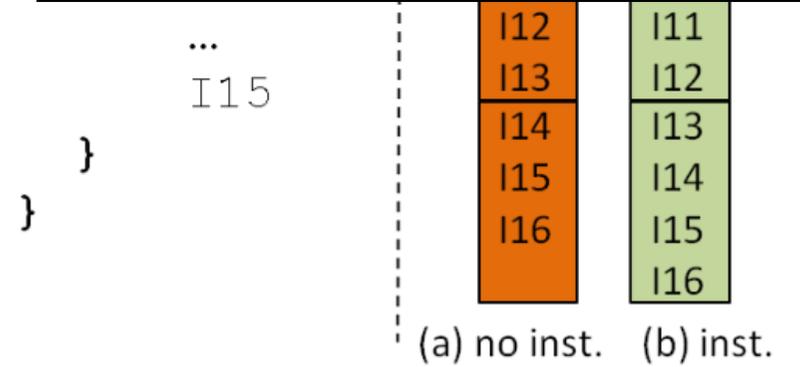


- 2 set – 2 way cache
- Time *ipro* < Time *opro*

# Removing the code: example



$$ET_{iprog} = ET_{oprogram} + \left( \Delta_{icode}^{core-exec} + \Delta_{icode}^{chip-exec} + \Delta_{icode}^{collect} \right) + \Delta_{icode}^{malign}$$



- 2 set – 2 way cache
- Time *iprogram* < Time *oprogram*

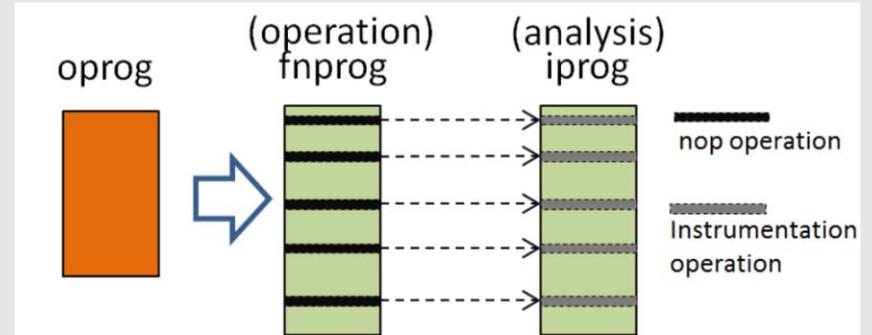
# Our approach: goals

- ❑ G1:
  - Execution time (version of the program for WCET analysis) > execution time (version of the program used during operation)
    - Reliability
- ❑ G2 (secondary):
  - Reduce overhead of the program used at operation in
    - memory size and
    - average execution time

# Proposal

## □ Three versions of the program:

- Original (*oprog*)
- Functionally neutral (*fnprog*)
- Instrumented (*iprog*)



## □ *fnprog* (operation):

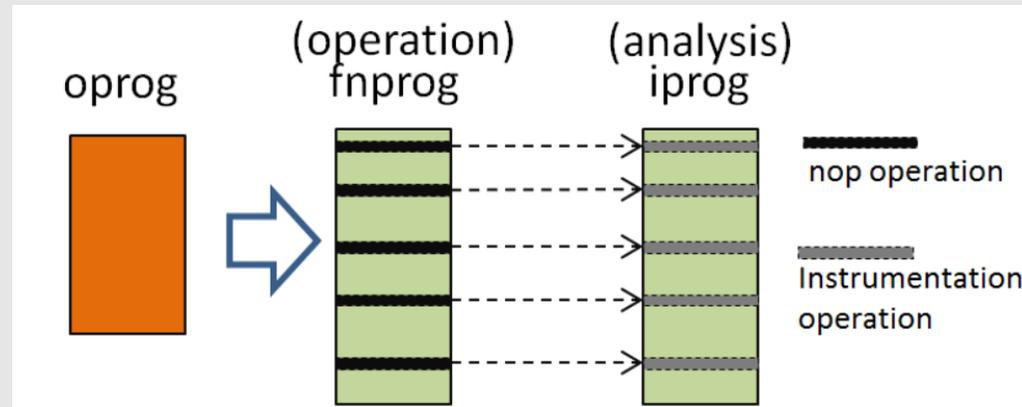
- Generated from *oprog* by inserting nop instructions at desired instrumentation points

## □ *iprog* (analysis):

- For timing analysis, nops are replaced by actual instr. Operations

**Number of nops inserted per ipoint in *fnprog* so that cache alignment of code in *fnprog* and *iprog* stays unchanged**

# Arguments to be made



- ❑ A1: *fnprog* provides the same functional output as *oprogram*
- ❑ A2: execution time (*iprogram*) > execution time (*fnprog*)
  - *iprogram* → analysis
  - *fnprog* → operation
- ❑ Reduce overhead of *fnprog*

# A1: *fnprog* = *oprog* functionally speaking

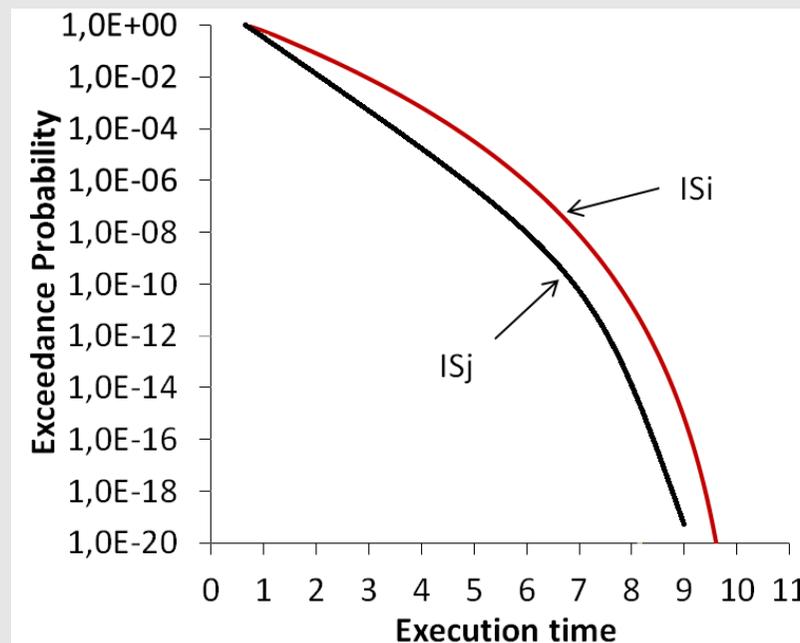
- ❑ ‘*fnprog* = *oprog* + nops’
  
- ❑ A nop operation:
  - 1) by definition performs no operation
  - 2) its does not change status flags or any other control registers
  - 3) generates neither interrupts nor exceptions
  - 4) uses no architectural (programmer accessible) register
    - Allows inserting nops anywhere in the code
  - 5) has no input and no output (register) dependences
  
- ❑ From all these properties it follows that *fnprog* cannot change the functional behaviour of *oprog*

# A2: $et(iprog) > et(fnprog)$

## Measurement-Based Probabilistic Timing Analysis

MBPTA[5]:

- $IS_i$  = instruction sequence
- $pET(IS_i)$  = its probabilistic execution time (pET)
- $IS_i = IS_j + \{\text{instruction}\} \rightarrow pET(IS_i) \geq pET(IS_j)$ 
  - For any cut-off probability the exec. time of  $IS_i \geq$  exec. time of  $IS_j$ .



This argument can also be made for standard MBTA

# Average performance

## □ Nops:

- usually take a few cycles to execute
- The processor may even strip them out from the pipeline before they reach the execution stage.

## □ Instrumentation instructions:

- Usually need to access off-core (or off-chip) resources such as I/O ports or trace buffers, thus incurring longer execution times.

# Setup

- ❑ Cycle-accurate simulator
- ❑ Cache:
  - 4KB L1 instruction- and data-caches
  - 128 sets and 2 ways each
  - Random placement and replacement
- ❑ Latencies:
  - The access latency to the L1 caches is 1 cycle
  - The access latency to main memory is 28 cycles.
- ❑ Instrumentation overhead:
  - For the instrumentation instructions, we assume they have the cost of 2 cycles.

# Benchmarks

## □ EEMBC automotive benchmarks:

- a2time(A2), aifftr(AI), aifirf(AF), aiifft(AT), bitmnp(BI), cacheb(CB), canrdr(CN), idctrn(ID), iirflt(II), matrix(MA)

## □ Railway case-study application

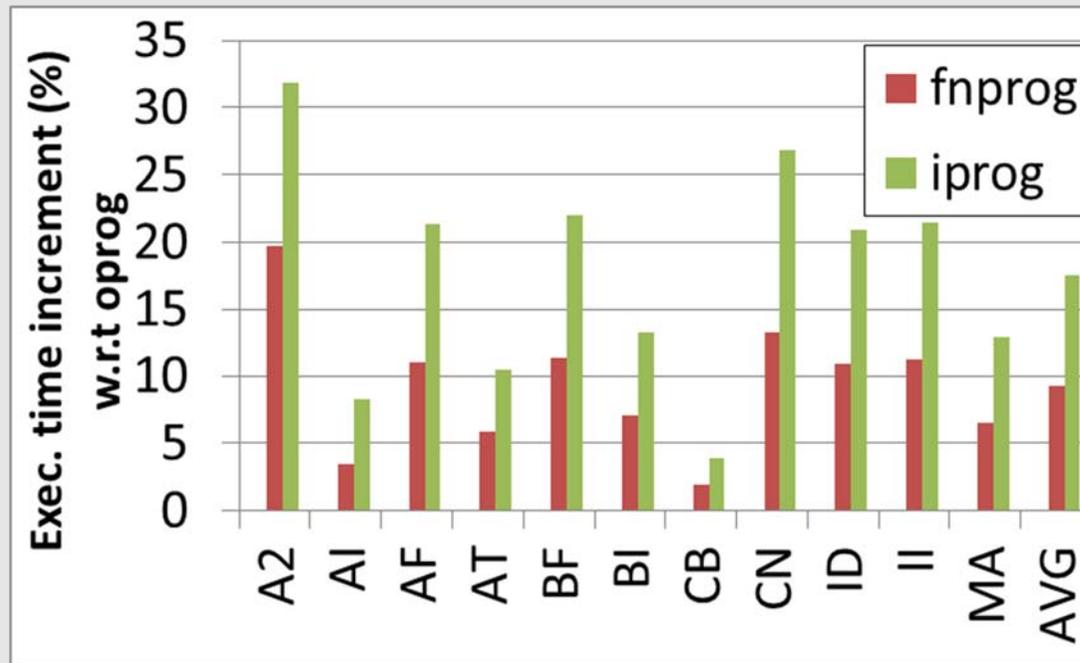
- Part of the European Railway Traffic Mgmt. System (ERTMS)
- On-board unit of the ERTMS, called European Train Control System (ETCS).
- We consider 10 different input sets (S0 to S9)

# Results: EEMBC. Code & time overhead

- Code size and exec. time increase (bb instrumentation)
  - fnprog and iprog w.r.t oprog

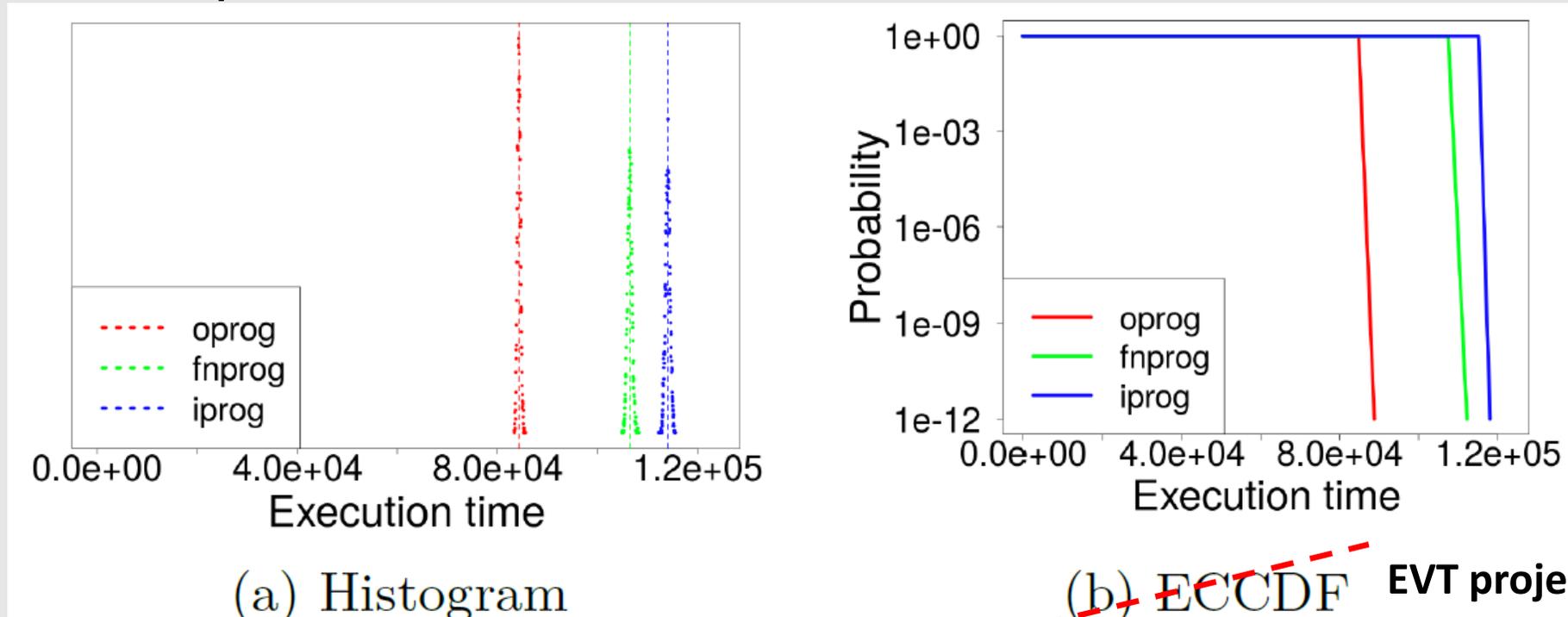
no. instruct.	Code Size	execution time fnprog	execution time iprog
1 inst./2 inst.	6.87%/13.74%	4.35%/9.28%	8.33%/17.54%

- Execution Time overhead (breakdown per task)



# Results: EEMBCs. pWCET results

## Example for a2time



## Results all benchmarks @ cutoff probability of 10e-12

prog.	A2	AI	AF	AT	BF	BI	CB	CN	ID	II	MA
fnprog	26.4%	3.8%	11.6%	7.1%	11.5%	11.9%	2.1%	14.1%	12.3%	11.9%	6.4%
iprog	33.0%	9.3%	22.1%	12.4%	22.0%	16.8%	4.0%	27.1%	23.3%	21.6%	12.7%

# Results: Railway case study

- ❑ 2 instrumentation instructions per ipoint
- ❑ Code and execution time overhead results
  - Tighter on average than those for EEMBC
  - Average pWCET estimate increase estimates across Sx
    - 8.7% (*fnprog*)
    - 11.9% (*iprogram*)

prog.	S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
<i>fnprog</i>	8.4%	7.6%	9.5%	9.1%	8.1%	9.5%	9.4%	8.3%	8.6%	8.9%
<i>iprogram</i>	11.5%	10.4%	12.1%	12.3%	12.2%	13.3%	12.4%	11.9%	12.2%	11.1%

■ Table 3 pWCET estimates for  $10^{-12}$  for *fnprog* and *iprogram* w.r.t to that for *oprogram*

- ❑ Code size increase
  - 12%
  - less than the average incurred with the EEMBC benchmarks

# Conclusions

- ❑ We presented an approach to
  - mitigate the impact of instrumentation code to prevent cache misalignments from occurring between the *ipro* and *opro*
  - while incurring low overhead in terms of execution time
- ❑ We build upon the use of *functionally-neutral* operations such as nops
  - Easy to show that the program version to be deployed that is functionally equivalent to the original program
  - Has a provable lower execution time than the instrumented version
- ❑ Future work:
  - Evaluate the fnprog approach in a real hardware platform and a commercial timing analysis tool



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