

BEST: a Binary Executable Slicing Tool and its use to improve Model Checking-based WCET Analysis

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1. Introduction

Motivation

Challenge

2. Program Abstraction using Program Slicing

Overview of Program Slicing

Abstracting models of programs

Tool implementation

3. Experimental results

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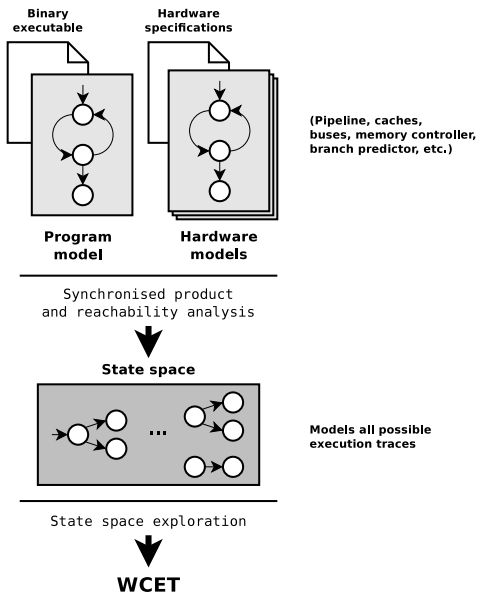
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Introduction

Motivation



Introduction

Motivation

modularity network of timed automata

tightness exact cache analysis

- ▶ arbitrary policies (not only LRU nor PLRU)

witness initial hardware and software configuration

binary level no high level source code analysis

- ▶ compiler independent

Introduction

Challenge

Limitations

- ▶ suffer of the state space explosion
 - ▶ tailored for embedded microcontrollers

Challenges

- ▶ abstracting models of hardware components [4]
- ▶ **abstracting models of programs** [1, 3, 6]
 - ▶ Cassez et al., 2013

Program Abstraction using Program Slicing

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Program Abstraction using Program Slicing

Overview of Program Slicing

Introduced by Weiser in 1981 [7]

- ▶ given a *program* $P \subseteq L \times I$, $\forall (l, i), (l, i') \in P, i = i'$ with
 - ▶ L a finite set of labels
 - ▶ I a finite set of instructions operating over V
 - ▶ V the set of variables of P
- ▶ and a *criterion* $C = (l, v)$ with
 - ▶ $l \in L$ a label and
 - ▶ $v \subseteq V$ a subset of variables
- ▶ a *slice* S_C is a subset of P
with the same semantics as P wrt. criterion C

Program Abstraction using Program Slicing

Overview of Program Slicing

The slice $S_{(l,v)}$

- ▶ is a valid program
- ▶ that computes values for the subset v
 - ▶ same as with the original program P
 - ▶ to the point of execution l
- ▶ is obtained by deleting zero or more “lines” from P

Program Abstraction using Program Slicing

Overview of Program Slicing

```
00003000 <_start>:
    3000:  li    r1,1           ;r1 <- 1
    3004:  ori   r1,r1,49296 ;ri <- r1 | 49296
    3008:  bl    3010          ;call main
0000300c <loop>:
    300c:  b     300c           ;branch
00003010 <main>:
    3010:  li    r8,29           ;r8 <- 29
    3014:  li    r10,1          ;r10 <- 1
    3018:  mtctr r8             ;ctr <- r8
    301c:  li    r9,1           ;r9 <- 1
    3020:  b     3028           ;branch
    3024:  mr    r9,r3           ;r9 <- r3
    3028:  add   r3,r9,r10       ;r3 <- r9+r10
    302c:  mr    r10,r9          ;r10 <- r9
    3030:  bdnz  3024           ;ctr--,
                                ;branch if ctr!=0
    3034:  blr                    ;return
```

$$C = (3030, \{ctr\})$$

Program Abstraction using Program Slicing

Overview of Program Slicing

```
00003000 <_start>:
    3000:  li    r1,1           ;r1 <- 1
    3004:  ori    r1,r1,49296 ;ri <- r1 | 49296
    3008:  bl    3010          ;call main
0000300c <loop>:
    300c:  b     300c            ;branch
00003010 <main>:
    3010:  li    r8,29           ;r8 <- 29
    3014:  li    r10,1          ;r10 <- 1
    3018:  mtctr r8           ;ctr <- r8
    301c:  li    r9,1           ;r9 <- 1
    3020:  b     3028            ;branch
    3024:  mr    r9,r3           ;r9 <- r3
    3028:  add   r3,r9,r10       ;r3 <- r9+r10
    302c:  mr    r10,r9          ;r10 <- r9
    3030:  bdnz 3024           ;ctr--,
                                           ;branch if ctr!=0
    3034:  blr                    ;return
```

$$C = (3030, \{ctr\})$$

Program Abstraction using Program Slicing

Overview of Program Slicing

- ▶ dataflow equation-based or graph-based
 - ▶ fixpoint computation or
 - ▶ reachability analysis
- ▶ slicing binary executables
 - ▶ a closed issue [5] (although not trivial)
 - ▶ multiple graph computation from a CFG
 - ▶ reachability analysis on the final graph

Program Abstraction using Program Slicing

Abstracting models of programs

An instruction has

- ▶ a timing behavior due to its
 - ▶ class of instruction → number of execution cycles
 - ▶ data dependencies → pipeline stall
 - ▶ memory access → cache delay
- ▶ and a semantics
 - ▶ updates the system state

→ We can abstract semantics of some instructions while keeping the timing behavior of the program

→ Variables used only by abstracted instructions can be removed from the model thus reducing the overall state space

Program Abstraction using Program Slicing

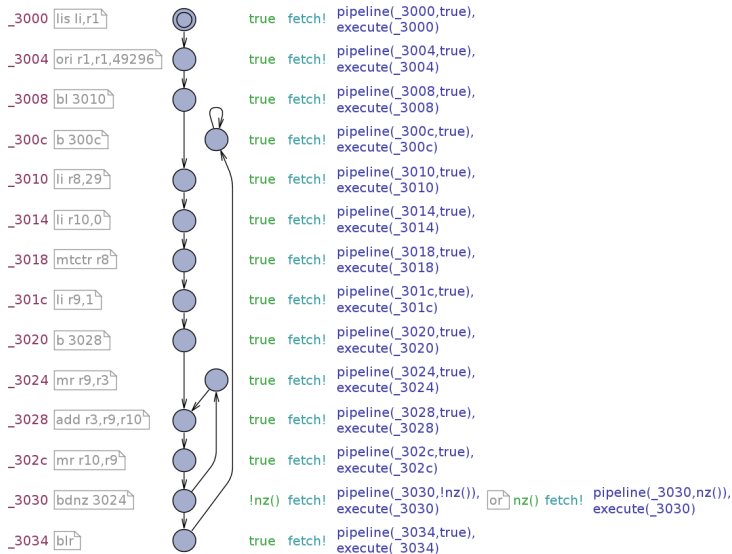
Abstracting models of programs

How to abstract a model of program?
(but not its timing behavior)

- ▶ abstract model must contain all paths from original model
 - ▶ i.e. contain all control instructions and their dependencies
- ▶ we can use program slicing to find these instructions
 - ▶ criteria are chosen wrt. the previous constraint as follows:
 $\{(l, v) \mid \exists i, (l, i) \in P$
and i is a conditional branching instruction
and v is the subset of variables used by i at $l\}$

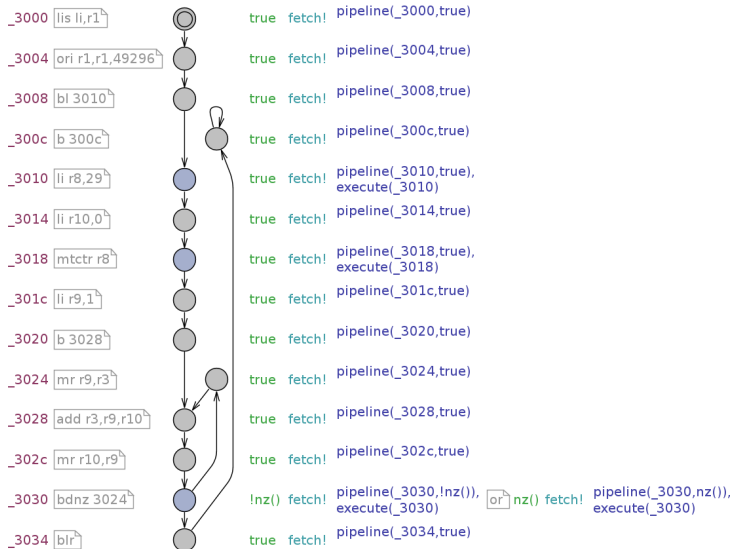
Program Abstraction using Program Slicing

Abstracting models of programs



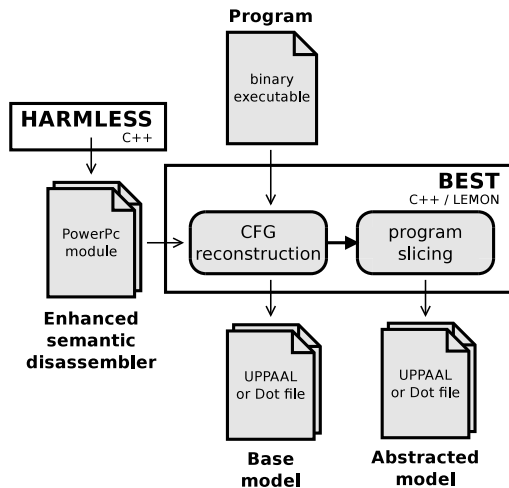
Program Abstraction using Program Slicing

Abstracting models of programs



Program Abstraction using Program Slicing

Tool implementation



Experimental results

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Experimental results

Methodology

- ▶ use of Mälardalen WCET benchmarks
- ▶ excluding programs containing
 - ▶ switch-case statements
 - ▶ floating-point arithmetic
 - ▶ recursive programs
- ▶ multiple compilers and optimization options
 - ▶ GCC 5.3.1 (-O0, -O1, -O2, -O3)
 - ▶ COSMIC C 4.3.7 (-no, *default*)
 - ▶ targeting the PowerPC 32 bits instruction set
- ▶ sums up to 96 binaries
- ▶ use of Trampoline RTOS [2] services
 - ▶ not documented on our paper

Experimental results

Results

Source file	Gcc				Cosmic C	
	-O0	-O1	-O2	-O3	-no	<i>default</i>
adpcm.c	224/1858, 88%	357/966, 63%	421/1094, 62%	348/1775, 80%	398/1282, 69%	338/1064, 68%
Average	78%	63%	62%	65%	66%	63%
	67%				64%	

- number of instructions in the slice/total number of instructions, gain in percentage.
- execution time negligible (always < 1 sec.)

Experimental results

Results

Source file	GCC				Cosmic C	
	-O0	-O1	-O2	-O3	-no	default
adpcm.c	11/17, 35%	28/32, 13%	26/28, 7%	33/36, 8%	22/37, 41%	22/37, 41%
Average	38%	35%	36%	37%	59%	54%
	37%				57%	

→ number of registers in the slice/total number of registers, gain in percentage.

→ execution time negligible (always < 1 sec.)

Future work

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Future work

- ▶ improve support of interprocedurality (straightforward)
- ▶ extend data dependency analysis to stack frames and initialized data
 - ▶ bigger slices but not necessarily bigger state space
- ▶ modeling the PowerPC e200z4 core
 - ▶ no data cache
 - ▶ instruction cache
 - ▶ 2 or 4-ways associative
 - ▶ pseudorandom (global FIFO)
 - ▶ branch prediction, . . .
- ▶ modeling the MPC5643L microcontroller
 - ▶ two PowerPC e200z4 cores
 - ▶ XBAR crossbar switch
 - ▶ multiple masters / multiple slaves
 - ▶ per slave policy (FP or RR)
- ▶ WCET analysis of parallel programs

Conclusion

- ▶ abstract models of program
 - ▶ for Model Checking-based WCET analysis
 - ▶ based on program slicing

- ▶ a binary executable slicing tool
 - ▶ instruction set independent
 - ▶ free software (GNU GPL)
 - ▶ promising experimental results

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Experimental results

Detailed results

Source file	Gcc				COSMIC C	
	-00	-01	-02	-03	-no	default
adpcm.c	1858/224, 88%	966/357, 63%	1094/421, 62%	1775/348, 80%	1282/398, 69%	1064/338, 68%
bs.c	82/27, 67%	38/19, 50%	28/18, 36%	28/18, 36%	54/28, 48%	35/18, 49%
bsort100.c	141/39, 72%	65/24, 63%	58/18, 69%	58/18, 69%	74/34, 54%	66/34, 48%
cnt.c	193/44, 77%	104/38, 63%	87/24, 72%	1124/81, 93%	128/25, 80%	112/23, 79%
compress.c	725/271, 63%	529/214, 60%	530/247, 53%	752/316, 58%	591/253, 57%	501/228, 54%
crc.c	295/44, 85%	162/50, 69%	141/47, 67%	210/98, 53%	186/112, 40%	148/81, 45%
expint.c	187/33, 82%	135/50, 63%	27/5, 81%	27/5, 81%	115/48, 58%	93/40, 57%
fdct.c	662/11, 98%	185/6, 97%	205/6, 97%	692/3, 99%	317/6, 98%	218/6, 97%
fibcall.c	58/12, 79%	32/10, 69%	14/3, 79%	14/3, 79%	29/8, 72%	21/8, 62%
fir.c	137/21, 85%	79/34, 57%	79/33, 58%	79/33, 58%	87/35, 60%	74/30, 59%
janne_complex.c	75/21, 72%	39/21, 46%	40/29, 28%	36/26, 28%	41/20, 51%	30/20, 33%
jfdctint.c	505/29, 94%	195/9, 95%	219/9, 96%	795/6, 99%	255/9, 96%	205/9, 96%
matmult.c	196/36, 82%	120/42, 65%	110/43, 61%	103/38, 63%	135/20, 85%	118/20, 83%
ndes.c	936/162, 83%	474/160, 66%	563/236, 58%	886/522, 41%	653/118, 82%	576/112, 81%
ns.c	115/35, 66%	65/30, 54%	46/27, 41%	181/88, 51%	69/33, 52%	54/29, 46%
prime.c	146/63, 57%	56/38, 32%	48/30, 38%	31/14, 55%	95/46, 52%	82/42, 49%
Average	78%	63%	62%	65%	66%	63%
	67%				64%	

→ number of instructions in the slice / total number of instructions,
gain in percentage.

Experimental results

Detailed results

Source file	Gcc				CosMIC C	
	-O0	-O1	-O2	-O3	-no	default
adpcm.c	11/17, 35%	28/32, 13%	26/28, 7%	33/36, 8%	22/37, 41%	22/37, 41%
bs.c	7/11, 36%	10/13, 23%	9/10, 10%	9/10, 10%	10/14, 29%	11/13, 15%
bsort100.c	9/12, 25%	13/18, 28%	11/16, 31%	11/16, 31%	13/15, 13%	13/15, 13%
cnt.c	10/15, 33%	13/18, 28%	10/16, 38%	10/18, 44%	10/37, 73%	10/37, 73%
compress.c	15/19, 21%	26/31, 16%	30/33, 9%	32/35, 9%	21/37, 43%	21/37, 43%
crc.c	8/17, 53%	14/23, 39%	10/19, 47%	9/19, 53%	18/37, 51%	18/37, 51%
expint.c	8/13, 38%	16/26, 38%	4/11, 64%	4/11, 63%	14/37, 62%	14/37, 62%
fdct.c	6/13, 54%	4/21, 81%	4/30, 87%	3/33, 91%	3/35, 91%	3/35, 91%
fibcall.c	7/11, 36%	7/12, 42%	3/7, 57%	3/7, 57%	6/12, 50%	6/10, 40%
fir.c	7/16, 56%	13/22, 41%	14/21, 33%	14/21, 33%	15/37, 59%	15/37, 59%
janne_complex.c	7/12, 42%	6/9, 33%	6/8, 25%	7/9, 22%	7/36, 81%	7/8, 13%
jfdctint.c	8/11, 27%	3/15, 80%	4/25, 84%	4/33, 88%	3/35, 91%	3/34, 91%
matmult.c	10/19, 47%	15/20, 25%	15/19, 21%	13/19, 32%	8/37, 78%	8/37, 78%
ndes.c	9/17, 47%	21/27, 22%	23/26, 12%	27/28, 4%	16/37, 57%	15/37, 59%
ns.c	9/14, 36%	13/17, 24%	13/15, 13%	9/12, 25%	14/37, 62%	14/36, 61%
prime.c	10/13, 23%	6/9, 33%	6/9, 33%	6/8, 25%	11/36, 69%	12/36, 67%
Average	38%	35%	36%	37%	59%	54%
	37%				57%	

→ number of memory locations in the slice / total number of memory locations, gain in percentage.